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Properties and Applications of (max,min)-linear Equations and Inequalities..

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CONTENT:

- ▶ Introduction
- ▶ Possible Applications - Motivating Examples
- ▶ Problem Formulation - General Scheme
- ▶ Generalizations and Further Research
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Motivation I.

- ▶ $\boxed{i} \longrightarrow \boxed{j} \longrightarrow \boxed{T},$
- ▶ $\boxed{T} \longrightarrow \boxed{j} \longrightarrow \boxed{i}.$
- ▶ $i \in I, j \in J, I, J$ finite index sets,
- ▶ "quality level" a_{ij} of $\boxed{i} \longrightarrow \boxed{j},$
- ▶ "quality level" b_{ij} of $\boxed{j} \longrightarrow \boxed{i},$
- ▶ "quality level" $x_j = ?$ of $\boxed{j} \longrightarrow \boxed{T}$
- ▶ "quality level" $y_j = ?$ of $\boxed{T} \longrightarrow \boxed{j}$
- ▶ "quality levels" fuzzy values from $[0, 1].$

Motivation I. continued

- ▶ Total "quality level" of $\boxed{i} \longrightarrow \boxed{j} \longrightarrow \boxed{T}$,
- ▶ is equal to $a_{ij} \wedge x_j \equiv \min(a_{ij}, x_j)$;
- ▶ Total "quality level" of $\boxed{T} \longrightarrow \boxed{j} \longrightarrow \boxed{i}$
- ▶ is equal to $b_{ij} \wedge y_j \equiv \min(b_{ij}, y_j)$;
- ▶ If $\boxed{j} \longrightarrow \boxed{T}$ is a two-way street, we have $x_j = y_j$.
- ▶ Levels x_j, y_j are bounded variables in $[0, 1]$, i.e.
 $x_j \in [\underline{x}_j, \bar{x}_j] \subset [0, 1], y_j \in [\underline{y}_j, \bar{y}_j] \subset [0, 1]$.
- ▶ $f_j(x_j), g_j(y_j)$ strictly monotone (increasing) or unimodal penalty functions (expenses).

Motivation I. - Continued.

- ▶ **Optimization Problem:**
- ▶ **Minimize** $f(x, y) \equiv \max(\max_{j \in J}(f_j(x_j)), \max_{j \in J}(g_j(y_j)))$
- ▶ **subject to**
- ▶ $\max_{j \in J}(a_{ij} \wedge x_j) R_i \max_{j \in J}(b_{ij} \wedge y_j) \quad \forall i \in I,$
- ▶ $x_j \in [\underline{x}_j, \bar{x}_j], y_j \in [\underline{y}_j, \bar{y}_j].$

- ▶ where R_i is equal to one of the relations $\leq, =, \geq.$
- ▶ "One sided" constraints of the form:

$$\max_{j \in J}(a_{ij} \wedge x_j) R_i b_i \quad \forall i \in I,$$

where $b_i \in (0, 1]$ are given can be obtained as a special case.

Motivation II. - Fuzzy Goals

- ▶ Let $I = \{1, \dots, n\}$, $J = \{1, \dots, n\}$;
- ▶ Let two groups of m fuzzy sets A_i, B_i (fuzzy goals) be given; their membership functions are $\mu_i(j) = a_{ij}$, $\nu_i(j) = b_{ij}$, $j \in J$, $i \in I$;
- ▶ We have to find fuzzy set X with membership function $\mu_X(j)$, $j \in J$, such that certain requirements concerning A_i, B_i , and X are fulfilled.
- ▶ Besides, we can look for optimal (in some sense) values $\mu_X(j)$, $j \in J$ satisfying the requirements.

Motivation II. - Fuzzy Goals

- ▶ Let for each $i \in I$, $\mu_{iX}(j) = a_{ij} \wedge x_j$, $\forall j \in J$,
 $\nu_{iX}(j) = b_{ij} \wedge x_j$, $\forall j \in J$;
- ▶ For each $i \in I$, functions μ_{iX} , ν_{iX} are the membership functions of the fuzzy intersection of fuzzy sets (A_i, X) , (B_i, X) respectively;
- ▶ We define for each $i \in I$ the heights of functions μ_{iX} , ν_{iX} as follows:

$$H_{A_iX}(\mu(j)) \equiv \max_{j \in J}(\mu_{iX}(j)),$$

$$H_{B_iX}(\nu(j)) \equiv \max_{j \in J}(\nu_{iX}(j)).$$

- ▶ We will assume that $f_j(\mu_X(j)), j \in J$ are given continuous increasing (in $\mu_X(j) = x_j$) penalty functions connected with the choice of $\mu_X(j)$;

▶ **Example 1**



$$\max_{j \in J} f_j(\mu_X(j)) \longmapsto \min$$

▶ subject to

$$H_{A_i X}(\cdot) \geq b_i, \quad \forall i \in I,$$

$$H_{B_i X}(\cdot) \geq c_i, \quad \forall i \in I,$$

where b_i, c_i are given nonnegative numbers.

▶ **Example 1 - reformulation**



$$\max_{j \in J} f_j(x_j) \longmapsto \min$$

▶ subject to

$$\max_{j \in J} (a_{ij} \wedge x_j) \geq b_i, \forall i \in I$$

$$\max_{j \in J} (b_{ij} \wedge x_j) \geq c_i, \forall i \in I$$

$$x_j \in [0, 1] \quad \forall j \in J$$

▶ **Example 2**



$$\max_{j \in J} f_j(\mu_X(j)) \mapsto \min$$

▶ subject to

$$H_{A_i X}(\cdot) = H_{B_i X}(\cdot), \forall i \in I$$

► **Example 2 - reformulation**



$$\max_{j \in J} f_j(x_j) \longmapsto \min$$

► subject to

$$\max_{j \in J} (a_{ij} \wedge x_j) = \max_{j \in J} (a_{ij} \wedge x_j) \quad \forall i \in I,$$

$$x_j \in [0, 1] \quad \forall j \in J.$$

General "Standard" Problem Formulation - Feasible Set.

- ▶ $J = \{1, \dots, n\}$, $I = \{1, \dots, m\}$,
 $R = (-\infty, +\infty)$, $R_+ = [0, +\infty)$,
- ▶ $R^n = R \times \dots \times R$ (n -times), $x^T = (x_1, \dots, x_n) \in R^n$,
superscript T means transposition.

- ▶ a_{ij} , b_{ij} nonnegative $\forall i \in I, j \in J$ are given,



$$a_i(x) \equiv \max_{j \in J} (a_{ij} \circ x_j) \quad \text{for all } i \in I,$$

- ▶ where \circ denotes one of the operations \wedge , $+$, $;$



$$b_i(x) \equiv \max_{j \in J} (b_{ij} \circ x_j) \quad \text{for all } i \in I,$$

- ▶ $M(\underline{x}, \bar{x}) \equiv \{x \in R^n ; a_i(x) = b_i(x) \quad \forall i \in I, \underline{x} \leq x \leq \bar{x}\}$

General "Standard" Formulation - Optimization Problem.



▶ **Minimize** $f(x) \equiv \max_{j \in J} f_j(x_j)$

▶ **subject to**

▶ $x \in M(\underline{x}, \bar{x})$.



▶ where $f_j : [0, 1] \rightarrow R$, $j \in J$ are continuous strictly increasing or unimodal functions.

Formulation of the Optimization Problem - Continued.

- ▶ In what follows we will consider the case, where $\circ = \wedge$, where $\alpha \wedge \beta \equiv \min(\alpha, \beta)$.
- ▶ i. e. we will consider the following problem:

▶ **Minimize $f(x)$ subject to**

▶

$$\max(a_{ij} \wedge x_j) = \max_{j \in J}(b_{ij} \wedge x_j) \quad \forall i \in I,$$

▶

$$\underline{x} \leq x \leq \bar{x}$$

Properties of the Feasible Set.

▶ Lemma 1

- ▶ **(1) Let $M(\bar{x}) \equiv \{x \in M ; a_i(x) = b_i(x), \forall i \in I, x \leq \bar{x}\}$.
Then $M(\bar{x}) \neq \emptyset$.**
 - ▶ **(2) If $M(\underline{x}, \bar{x}) \neq \emptyset$, then there exists always its maximum element x^{\max} , i.e. there exists an element $x^{\max} \in M(\underline{x}, \bar{x})$ such that $x \leq x^{\max} \forall x \in M(\underline{x}, \bar{x})$.**
 - ▶ **(3) $M(\underline{x}, \bar{x}) \neq \emptyset$ if and only if $\underline{x} \leq x^{\max}$.**
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- ▶ **Remark**
 - ▶ There exists a polynomial ($O(n^3)$) algorithm for finding x^{\max} (see [Gavalec, Zimmermann, Kybernetika 2010]).

General Iteration Scheme - Application to (max, min)-linear Problems.

We apply the general iteration scheme to the problem

- ▶ **Minimize $f(x)$**
- ▶ **subject to**
- ▶ **$x \in M(\underline{x}, \overline{x})$.**
- ▶





Proposal of an Iteration Scheme - ALGORITHM I.

ALGORITHM I.

- 0 $\underline{f} := f(\underline{x}), \bar{f} := f(\bar{x});$
- 1 Find the maximum element x^{\max} of set $M(\bar{x});$
- 2 If $\underline{x} \not\leq x^{\max}$, then $M(\underline{x}, \bar{x}) = \emptyset$, STOP;
- 3 $\alpha := f(x^{\max}), \underline{f}(\alpha) := \underline{f}, \bar{f}(\alpha) := f(x^{\max});$
- 4 $\alpha := \underline{f}(\alpha) + (\bar{f}(\alpha) - \underline{f}(\alpha))/2$, set $\bar{x}_j(\alpha) := f_j^{-1}(\alpha) \forall j \in J$;
- 5 Find $x^{\max}(\alpha) \in M(\bar{x}(\alpha));$
- 6 If $\underline{x} \not\leq x^{\max}(\alpha)$, set $\underline{f}(\alpha) := \alpha$ go to **4**;
- 7 If $f(x^{\max}(\alpha)) - \underline{f}(\alpha) < \epsilon$, set $x(\epsilon)^{opt} := x^{\max}(\alpha)$, STOP.
- 8 $\bar{f}(\alpha) := f(x^{\max}(\alpha))$, go to **4**;

Extensions, Further Research.

- ▶ For $(\max, +)$ -linear or (\max, \cdot) -linear problems only pseudopolynomial algorithms [Bezém et al.].
- ▶ (\min, \max) - , $(\min, +)$ - or (\min, \cdot) -linear problems by analogy.
- ▶ For minimizing function $f(x)$ under one-sided constraints $\max_{j \in J} (a_{ij} \wedge x_j) \leq b_i \quad \forall i \in I$, there exists an exact algorithm see [Zimmermann, K. Theoretical computer Science 293(2003), pp.45 - 54].
- ▶ Exact (polynomial) optimization algorithms using the structure of the two-sided constraints is the subject of further research.
- ▶ Problems with objective function $f(x)$ and linear or convex constraints of the form: $M(\underline{x}, \bar{x}) \cap K$, where $K = \{x ; g_i(x_1, \dots, x_n) \geq 0\}$, where $g_i, i \in I$ are concave functions and g_j are strictly increasing in all variables $x_j, j = 1, \dots, n$.

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